



**Pakistan School**  
Kingdom of Bahrain

# Resolution of a Vector into its Rectangular Components.

**Class 11**

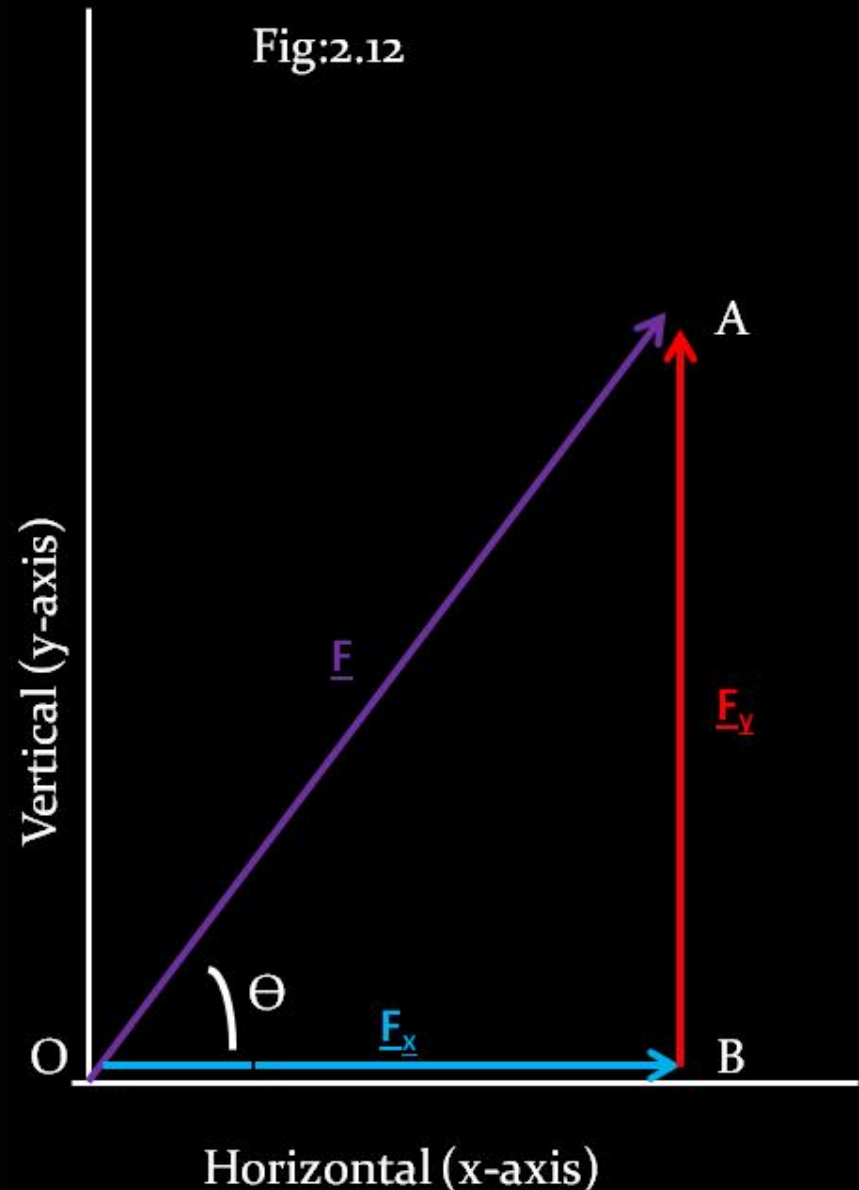
# Objective

- Students will be able to create a vector by resolution of vectors.

# Resolution of a Vector into its Rectangular Components.

- Consider a force vector  $F$ , which makes angle  $\theta$  with  $x$  — axis, In order to find its rectangular components, draw perpendicular from the head of vector, on  $x$  — axis and  $y$  — axis, which meet at point B and C respectively, as shown in fig. 2.12. Represent arrowheads at point B and C, pointing away from origin.
- $\underline{OB}$  and  $\underline{OC}$  are called rectangular components of given vector  $F$ , because they are at right angle with each other. Since  $\underline{OB}$  is along  $x$  — axis therefore, can be labeled as  $\underline{F_x}$  and  $\underline{OC}$  is acting along  $y$  — axis therefore, can be labeled as  $\underline{F_y}$ . In order to verify, how or why they are called rectangular components of  $\underline{F}$ , if we add them according to head-to-tail rule the resultant  $\underline{F}$  can be achieved, as shown in figure 2.12.
- In order to find magnitudes of  $\underline{F_x}$  and  $\underline{F_y}$  consider  $\Delta OAB$ , which is a right angle triangle. As we know,

Fig:2.12



In order to find magnitudes of  $\vec{F}_x$  and  $\vec{F}_y$  consider  $\Delta OAB$ , which is a right angle triangle. As we know,

$$\cos\theta = \frac{\text{base}}{\text{hypotenuse}} = \frac{F_x}{F} \Rightarrow F_x = F \cos\theta \dots (2.3)$$

Similarly

$$\sin\theta = \frac{\text{Perpendicular}}{\text{hypotenuse}} = \frac{F_y}{F} \Rightarrow F_y = F \sin\theta \dots (2.3)$$

- From Eq.2.3 and Eq. 2.4 magnitudes of  $F_x$  and  $F_y$  can be calculated.
- In Eq.2.3 and Eq. 2.4,  $\theta$  is the angle which  $F$  makes with positive x — direction in anti-clockwise sense.

Method to find the resultant of rectangular components of vector.

- If  $\vec{F}_x$  and  $\vec{F}_y$  are given then find their resultant simply by adding them according to head-to-tail rule (a scaled diagram is not required), a right angled triangle forms as shown in figure 2.12. To find magnitude of the resultant  $\vec{F}$  apply Pythagoras theorem as:  $(\text{Hypotenuse})^2 = (\text{Base})^2 + (\text{Perpendicular})^2$

$$\text{Or } (\vec{F})^2 = (\vec{F}_x)^2 + (\vec{F}_y)^2 \Rightarrow F = \sqrt{(\vec{F}_x)^2 + (\vec{F}_y)^2} \dots (2.5)$$

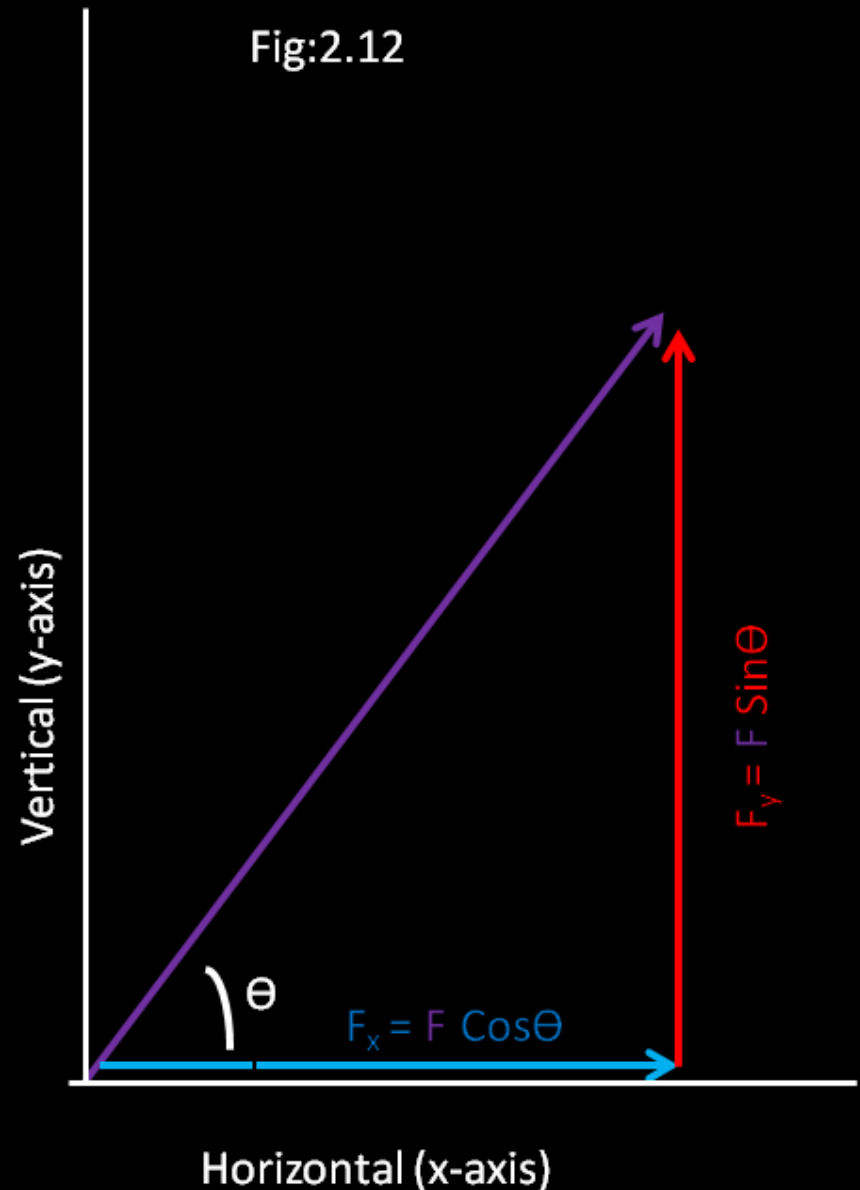
To find the direction,  $\tan\theta = \frac{\text{Perpendicular}}{\text{Base}} = \frac{F_y}{F_x}$

$$\theta = \tan^{-1}\left(\frac{F_y}{F_x}\right)$$

Eq 2.5 and Eq 2.6 can be used to find magnitude and direction of the resultant. In three dimensional cases.

$$F = \sqrt{F_x^2 + F_y^2 + F_z^2}$$

Fig:2.12



# Closure

- What is Resolution of vectors?
- Braking up of vectors into its components

# Home Work

- Write a note on resolution of vectors?
- Or
- Draw a chart about resolution of vectors