



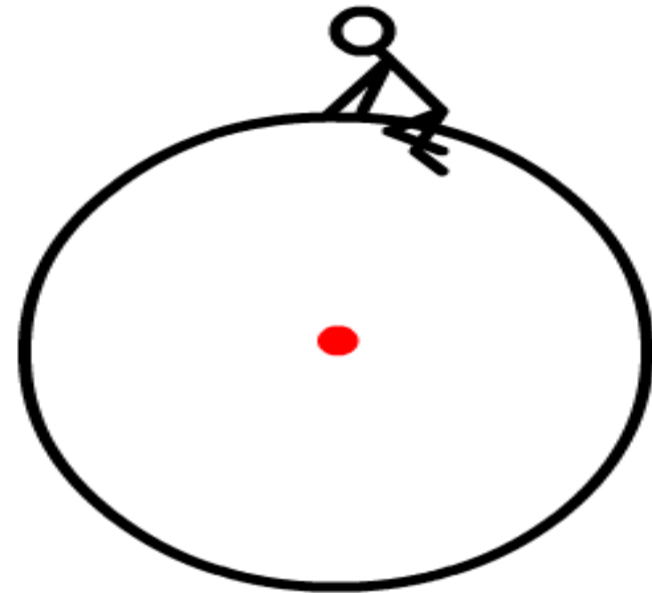
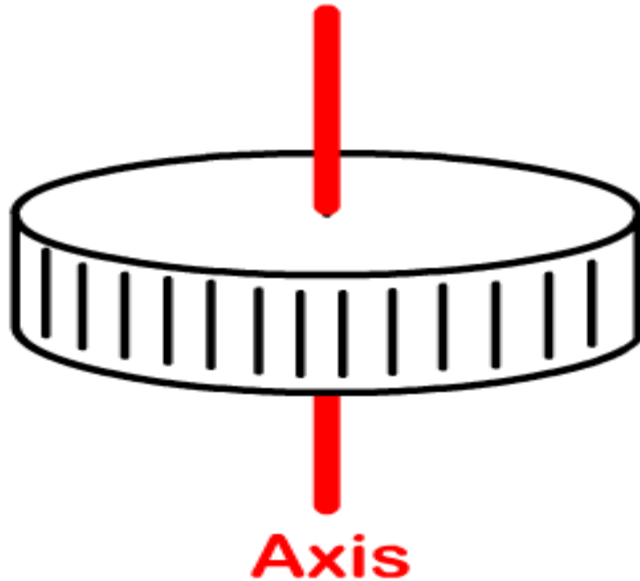
**Pakistan School**  
Kingdom of Bahrain

# Rules of the Class:

- 1) Always be **on time** for all your classes
- 2) Always **Respect** your all Class fellows.
- 3) Do not create any **disturbance**.
- 4) **Raise hand** if you have any question or you wish to answer any **question**.
- 5) Pay **attention** to your teacher.
- 6) **Please**, Enter into the class with your actual Name and CPR number.
- 7) Always follow your **Time Table**.

# Engaging Starter

## Rotation



## Revolution

# Learning Objectives:

By the end of the session, students will be able to:

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**1) Define Torque.**

**2) Differentiate between Axis of rotation, Line of action of force and Moment arm.**

# Grade 11<sup>th</sup> ” Physics ”

**Unit: 2** “**Vectors and**

**Equilibrium”**

**Topic:2.1** “**Torque”**

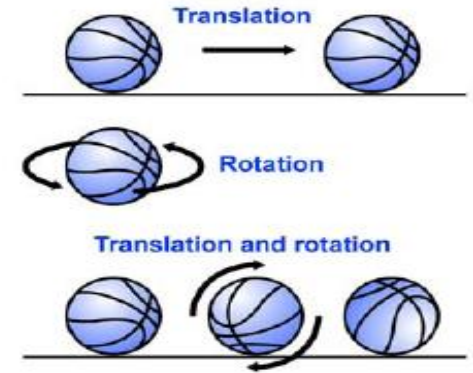
# Physics:

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Torque: (The moment of force)



# Torque: (Definition)



- The turning effect of a force about an axis of rotation.

Torque: is defined as the tendency to produce a change in rotational motion.

- A torque is an action that causes objects to rotate.
- A torque is required to rotate an object, just as a force is required to move an object in a line.

Dependence: Torque is created by force, but it also depends on where the force is applied and the point about which the object rotates.

- **For example**, a door pushed at its handle will easily turn and open, but a door pushed near its hinges will not move as easily. The force may be the same but the torque is quite different.

Torque

$$\begin{array}{ccccc} & \text{Lever arm} & & & \\ & (\text{m}) & & & \\ \text{Torque} & \tau = r \times F & \text{Force} & & \\ (\text{N}\cdot\text{m}) & & (\text{N}) & & \end{array}$$



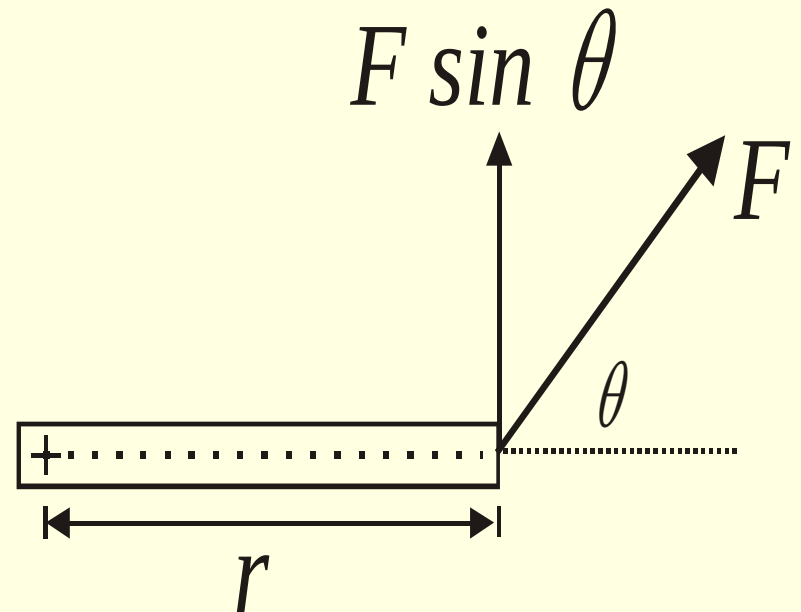
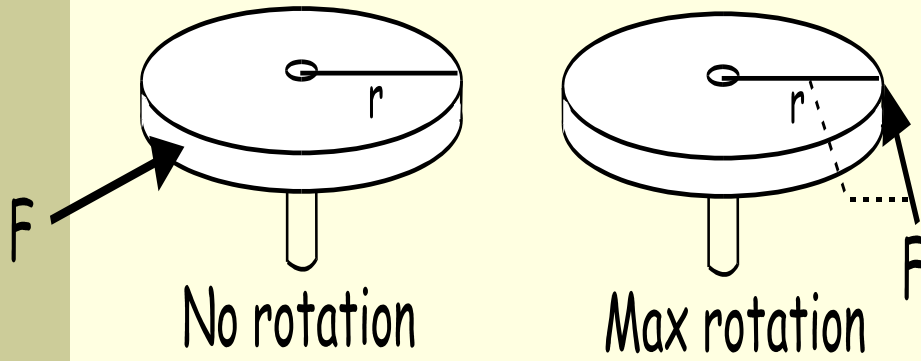
# Torque: (Example of vector or cross product)

- Torques change angular velocity. The symbol for torque is the Greek letter  $\tau$ . Torque is given by this equation:  $T = r \times F$  or
- $r$  is the distance from axis of rotation (**pivot**) to the line of action of force.
- This variable distance is often called the Moment arm or **lever arm**.

$$\tau = rF \sin \theta$$

- $F \sin \theta$  be the force component that is perpendicular to the moment arm

# Diagrammatic Analysis:



$$\tau = rF \sin \theta$$

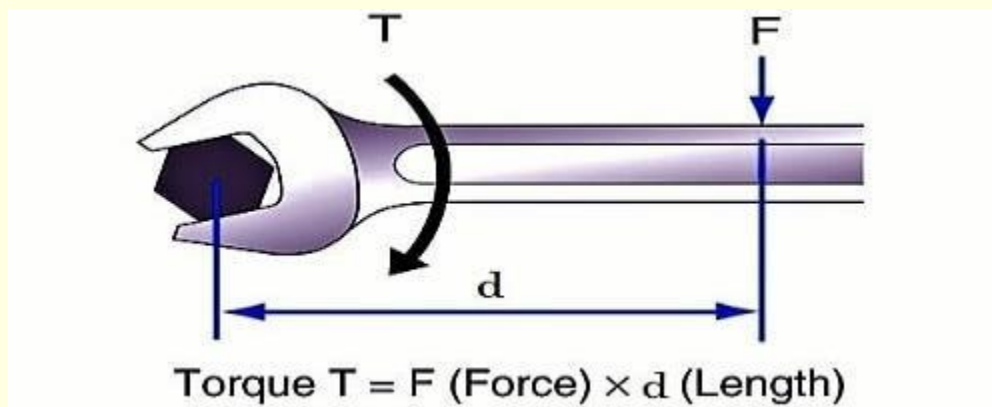
# Torque Units:

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- The unit for torque is going to be a **newton meter (N m)**.
- This looks very similar to the unit for work, the joule, but it is **quite different**.
- So energy and work are in **joules** and torque is left in Newton meters.

# Center of rotation: (Axis of rotation)

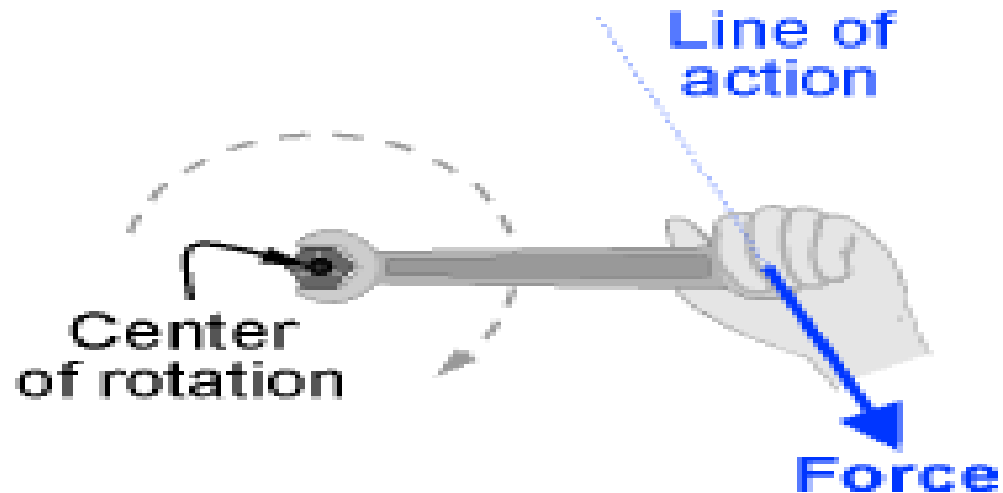
- The point or line about which an object turns is its center of rotation.
- For example, a door's center of rotation is at its hinges.
- A force applied far from the center of rotation produces a greater torque than a force applied close to the center of rotation.



# Line of action of force:

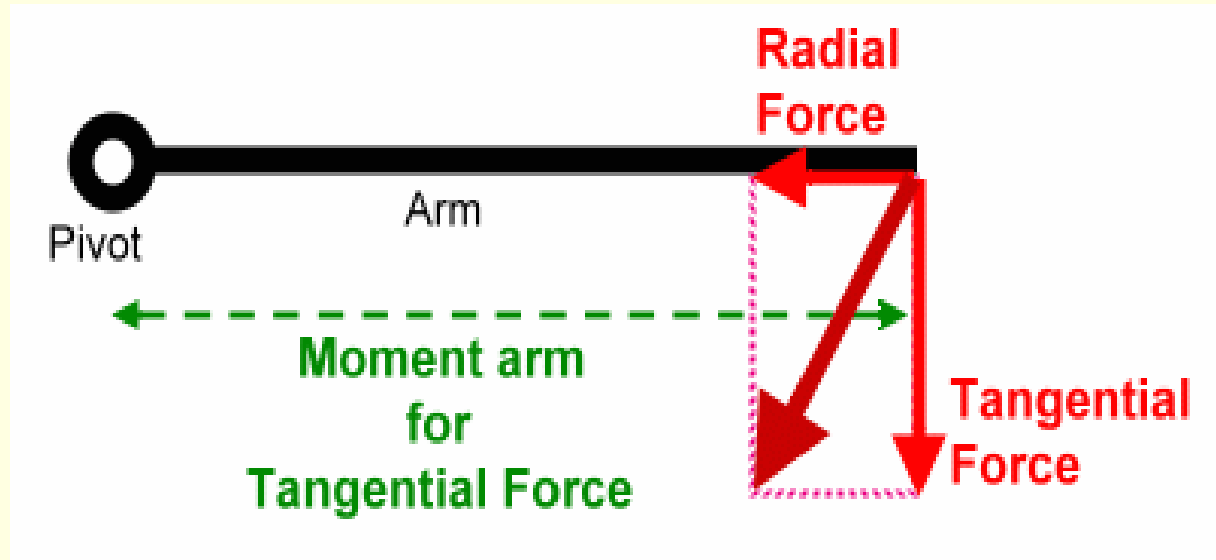
- Torque is created when the line of action of a force does not pass through the center of rotation.

## **The line of action of a force**



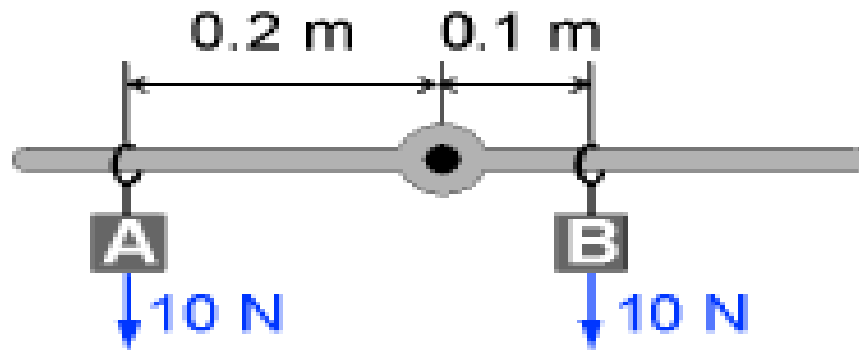
# Moment arm:

- The **Moment arm** is the perpendicular distance from axis of rotation to the line of action of force.



# Adding Torques: (Practice)

## Adding torques



$$\tau_A = +2 \text{ N} \cdot \text{m}$$

$$\tau_B = -1 \text{ N} \cdot \text{m}$$

$$\tau_A + \tau_B = +1 \text{ N} \cdot \text{m}$$

# Example:(Practice)

- A torque of 857 Nm is applied to flywheel that has a radius of 45.5 cm. What is the applied force?

$$\tau = Fr \quad F = \frac{\tau}{r} = 857 \text{ Nm} \left( \frac{1}{0.455 \text{ m}} \right) = \boxed{1880 \text{ N}}$$

# **Home Work**

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Assignment is given in uploaded notes.

# Closure

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- a) Define **moment arm**.
- b) Define **axis of rotation**.
- c) Define **torque**.
- d) Differentiate b/w axis of rotation and **momentarm**.
- e) Clock-wise torque is \_\_\_\_\_.
- f) Anti-Clock Wise torque is \_\_\_\_\_..

Thank you.....

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